® NINGBO DAGANG INI HYDRAULIC CO.,LTD.



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Product Shows & Applications



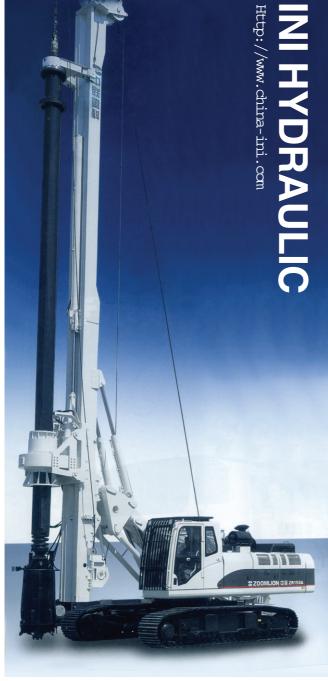
































Product Shows & Applications

































Brief Introduction



NINGBO DAGANG INI HYDRAULIC CO., LTD is situated in a state-level economic and technological development zone of BEILUN district, NINGBO. The factory covers almost 40,000 m², with 38,000 m² building area. The registered capital is 6,500,000 USD, and the total investment is 15,000,000 USD. Currently, the company is staffed with 400 employees, 20% amang whom are professional technicians. The company has a strong R&D team, led by the general manager—a professorate senior engineer, who takes special allowance from State Council. The team also includes one doctor, two masters, senior engineers, engineers and engineer trainees, and two retired German experts from ZF GROUP as honor employees. They will come to the factory to help and give advices once a year. Up to now, the company owns eight invention patents and thirty practical innovation and figure patents. Several other patents are under reviewing. The company is specialized in manufacturing of electro—hydraulic proportional valves, hydraulic motors, hydrostatic drives, hydraulic winches, planetary gearboxes, high accuracy rotary flow dividers and the whole set of hydraulic system. These patent products are widely used in engineer—ing machinery, petroleum, mining industry, geological exploration, ships, metallurgy, light industry, agriculture, landscape, environment and military industry. Now we are stepping into the international market, and our products are being exported to Southeast Asia, Middle East, Germany, USA, Netherlands, Turkey, India, Russia, Korea and other countries and regions around the world.

The company has more than 150 advanced manufacturing equipment, half of which were imported. 60% of all the machines are CNC, including three–dimension coordinate measuring machine, universal gear measuring machine, digital ultrasonic inspection machine, and universal tool microscope. A static hydrostatic drives lab and 12 factory test stands were established for product testing. The company passed ISO 9001 quality system certification, CCS certification and CE certification. The annual sales volume reaches 250 million RMB, with a production capacity of over 300 million RMB. The company was appraised as a state–level high–tech enterprise and is a patent pioneer enterprise.

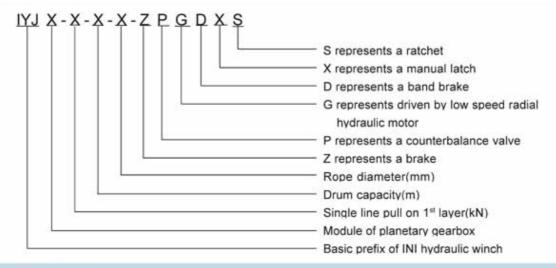


IYJ Hydraulic Winch Series

1. Brief Introduction

The IYJ hydraulic winch series use the patent technique of our company and consist of a variety of valve blocks with function of braking and single counterbalance valve, high speed hydraulic motor, Z type brake, KC type or GC type planetary gearbox, drum, frame and clutch. The user only needs to provide a hydraulic power pack and directional valve. Due to the winches fitted with diversified valve block, it not only simplified the hydraulic system, but also improved the reliability of the winches. In addition, the winches feature a high efficiency and power, low noise and energy consumption, and have a compact figure and good economic value. Therefore, the series have been widely applied to construction, petroleum, mining, geological drilling, ship and deck machinery. IYJ series hydraulic winches have been well sold in China, and also have been exported to the Middle-east, south-east Asia, India, Korea, Russia, Australia, US, Netherlands and so on,

2. Model Options

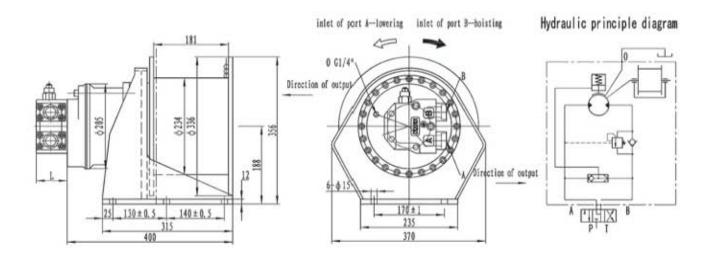


3. Options Example

IYJ334-75-88-22-ZPG represents that the hydraulic winch adopts a three stage planetary gearbox, and that the modules of the gearbox are 3,3 and 4 respectively. The rated single pull on 1st layer is 75kN, drum capacity is 88, rope diameter is 22 mm. the winch is fitted with brake, counterbalance valve, and is driven by a high speed axial hydraulic motor.

4. Parameter Description

- The total displacement represents the oil flow supply per revolution of the drum(mL/r).
- The oil flow supply indicates the theoretical flow of the pump when the volumetric efficiency is considered to be 90-94%.
- Maintain mandatory minimum of three wraps rope to be left on the drum at all times for safety.
- The working pressure differential represents the pressure drop between port A and port B.
- This winch series can be equipped with a rope roller, alarm system for the last three winding ropes, rope-guider, output shaft for rotation speed measurement, these items are optional. More options are available please contact the sales department.
- 5. There are other winch series available, such as IYJ-L free fall hydraulic winch series, IYJ-C hydraulic mooring winch series, ISYJ hydraulic winch series for truck, INYJ internal hydraulic winch series and so on, please refer to other catalogs of our company or contact the sales department.

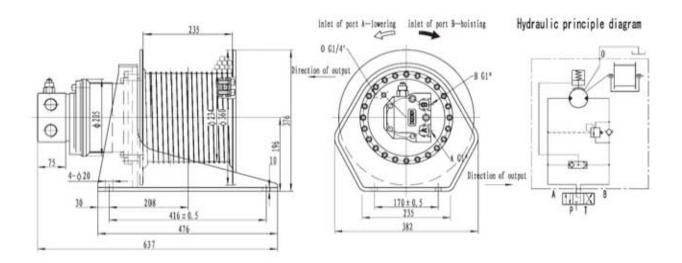


12170	The	1st layer	Total	Working pressure diff	Supply oil flow	Diameter of rope	Layer	Capacity of rope	Hydraulic motor	Gearbox mode	
Model	Pull (KN)	Rope speed (m/min)	(ml/rev)	(MPa)	(L/min)	(mm)		or rope		Museum Press	
IYJ2. 5A-5-73-8-ZP	5	60	370	14	30	8	1 2 3 4	16 34 53 73	INM05-75D60101	C2. 5 i=5	
IYJ2. 5A-10-61-10-ZP	10	30	755	15. 5	30	10	2 3 4	16 34 53 73 13 28 44 61 12 25 40 12 25 40 12	INM05-150D60101	C2. 5 i=5	
IYJ2. 5A-15-40-11-ZP	15	48	1057	13. 5	70	11	2 3	12 25 40	INW05-150120101	C2. 5 i=7	
IYJ2. 5A-17. 5-40-11-ZP	17.5	38	1337	13	70	11	2 3	12 25 40	INM05-2000120101	C2. 5 i=7	
IYJ2. 5A-20-40-11-ZP	20	38	1337	14. 7	70	11	2 3	12 25 40	INM05-2000120101	C2. 5 i=7	
IYJ2. 5A-25-37-12-ZP	25	38	1337	18	70	12	2 3	11 24 37	INM05-200D120101P	C2. 5 i=7	

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- 3. The winch is not designed for operation involving lifting or moving personnel.
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.

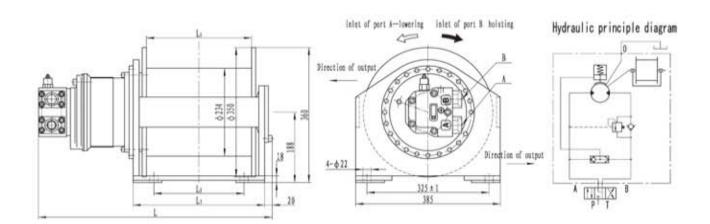
Distributors Model

Supply oil flow(L/min)	Mode!	A	В	L.
0-40	060101	M22x1.5	#22x1.5	65
40-90	0120101	ф35	ф35	75



	The 1st layer		Tota Working displacement pressure diff		Supply oil flow	Diameter of rope	Layer	Capacity of rope	Hydraulic motor	Gearbox model	
Model	Pull (KN)	Rope speed (m/min)	(ml/rev)	(MPa)	(L/min)	(mm)		(m)			
1YJ2. 5A-15-65-13-ZP	15	30	1337	10.5	55	13	2	14 29 46	INM05-200D120101	C2. 5 i=7	
							4			1-1	

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Basic model	Model	The	1st layer Rope speed	Total displacement	Working pressure diff.	Supply oil flow	Diameter of rope	Layer	Capacity of rope	Hydraulic motor	Gearbox mode	Weight
mouci		(KN)	(m/min)	(ml/rev)	(MPa)	(L/min)	(mm)		(m)			(kg)
ar.	IYJ2. 5-5-93-10-ZP	5	60	370	13	32	10	1 2 3 4	21 44 69 93	INM05-75D60101	C2. 5A i=5	130
1	IYJ2. 5-10-93-10-ZP	10	60	645	15	56	10	3	69 93 21 44 69 93 25 54 85 25 54 85 32 69 109	INM05-130D120101	C2. 5A i=5	130
2	IYJ2. 5-12-85-12-ZP	12	56	830	14	67	12	2 3	25 54 85	INM05-170D120101	C2. 5A i=5	160
4	IYJ2. 5-15-85-12-ZP	15	53	955	16	70	12	2 3	25 54 85	INM05-2000120101	C2. 5A i=5	160
3	IYJ2. 5-18-109-13-ZP	18	48	1057	16	70	13	2 3	32 69 109	INM05-1500120101	C2. 5 i=7	200
	IYJ2. 5-20-102-14-ZP	20	39	1337	14	70	14	2 3	30 64 102	INM05-2000120101	C2. 5 i=7	200
4	IYJ2. 5-22-130-14-ZP	22	39	1337	15. 6	70	14	2 3	30 64 102 38 82 130 38 82 130	INM05-2000120101	C2. 5 i=7	200
	IYJ2. 5-24-130-14-ZP	25	39	1337	18	70	14	2 3	38 82 130	INM05-2000120101	C2. 5 i=7	200

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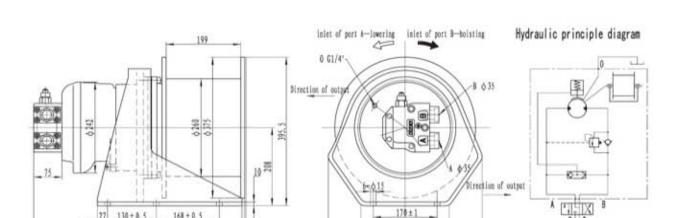
Profile Dimension

	Li (m)	Lz (m)	L3 (m)	Limi
-1	280	240	350	622
2	402	362	472	744
3	552	512	622	913
4	700	660	770	1100

Distributors Model

Supply oil flow(L/min)	Vodel	A	8
0-40	060101	M22x1.5	W22x1.5
40-90	0120101	ф35	ф35

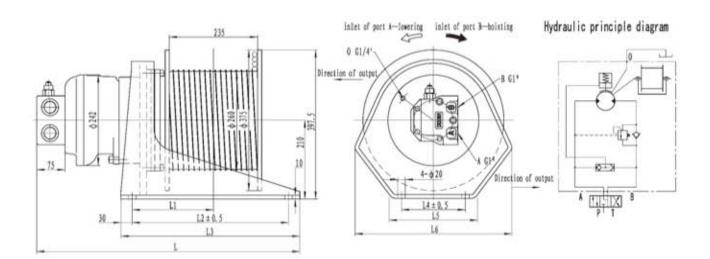
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1000	The	The 1st layer		Working pressure diff	Supply oil flow	Diameter of rope	Layer	Capacity of rope	Hydraulic motor	Gearbox mode	
Model	Pull (KN)	Rope speed (m/min)	(ml/rev)	(MPa)	(L/min)	(mm)	11000	(m)			
IYJ3A-20-62-12-ZP	20	45	1407	14.5	80	12	1 2 3 4	13 28 45 62 12	INM1-200D120101	C3 i=7	
IYJ3A-25-58-13-ZP	25	38	1701	15	80	13	1 2 3 4	12 26 42 58	INM1-250D120101	C3 i=7	
1YJ3A-30-58-13-ZP	30	32	2030	15. 2	80	13	1 2 3 4	26 42 58 12 26 42 58	INM1-3000120101	C3 i=7	
1YJ3A-35-55-14-ZP	35	30	2198	16. 4	80	14	1 2 3 4	11 24 39 55	INN1-3200120101	C3 i=7	

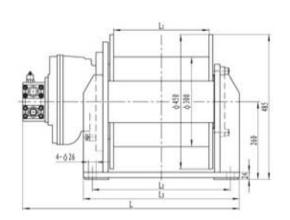
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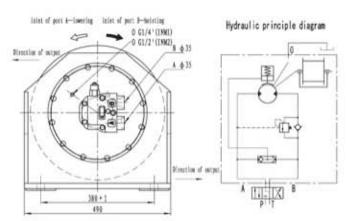


	The 1st layer		Total displacement	Working pressure diff	Supply oil flow	Diameter of rope	Layer	Capacity of rope	Hydraulic motor	Gearbox mode
Model	Pull (KN)	Rope speed (m/min)	(ml/rev)	(MPa)	(L/min)	(mm)		(m)	2	
IYJ3A-25-70-13-ZP	25	45	1701	14. 9	96	13	1 2 3 4	15 32 50 70	INM1-250D120101	C3 i=7
IYJ3A-35-70-13-ZP	35	45	2380	15	120	13	1 2 3 4	15 32 50 70	INM1-3500240101	C3 i=7

Model	L	L1	L2	L3	L4	L5	L6
IYJ3A-25-70-13-ZP	700	216	416	476	170	215	417
1YJ3A-35-70-13-ZP	745	245	490	550	285	368	398

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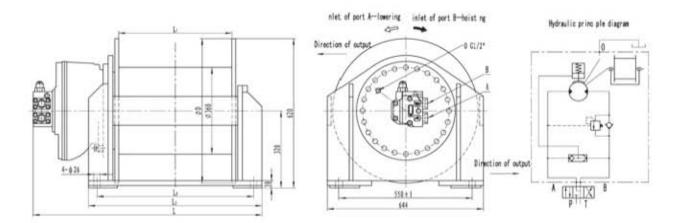


Basic		The	1st layer	Total	Working	Supply oil flow	Diameter	Layer	Capacity	Hydraulic motor	Gearbox model	Wolahi
mode l	Model	Pull (KN)	Rope speed (n/min)	(ml/rev)	pressure diff (MPa)	(L/min)	of rope (mm)	200	of rope (m)	nyulaulu liluul	Geardox model	(kg)
	IYJ3-20-76-14-ZP	20	43	1701	13. 7	80	14	2 3	17 36 57 76	INM1-2500120101	C3 i=7	170
1	IYJ3-24-76-14-ZP	24	37	2030	13. 8	80	14	2 3		INM1-3000120101	C3 i=7	170
	IYJ3-25-99-14-ZP	25	37	2030	14.5	80	14	2 3	36 57 76 22 47 73 99 22	INM1-3000120101	C3 i=7	230
2	IYJ3-30-99-14-ZP	30	34	2198	16.8	80	14	2 3	22 47 73	INM2-3200120101	C3 i=7	230
	IYJ3-32-92-16-ZP	32	55	2711.5	14. 0	160	16	2 3	47 73 99 27 58 92 27 58 92 27 58 92 36 76 120 32 68	INM2-5000240101	C3D i=5. 5	300
3	IYJ3-35-92-16-ZP	35	48	3107.5	13. 2	160	16	2 3	27 58 92	INM2-6000240101	C3D i=5.5	300
	IYJ3-40-120-16-ZP	40	48	3107.5	15. 0	160	16	2 3	36 76 120	INM2-6000240101	C3D i=5.5	370
4	IYJ3-42-108-18-ZP	42	44	3426.5	14. 4	160	18	2	32 68 108	INM2-6300240101	C3D i=5.5	370

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Profile Dimension

Г		Lt (m)	Lz (w)	Limi	1 (m)
Г	1	245	387	447	625
Г	2	320	462	522	750
ľ	3	450	592	652	880
ľ	4	587	729	789	1017



Basic		The	1st layer	Total	Working	Supply oil flow	Diameter		Capacity			
model	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	(L/min)	of rope (mn)	Layer	of rope	Hydraulic motor	Gearbox model	
	IYJ4-40-89-16-ZP	40	60	3450	16. 1	195	16	2 3	27 57 89	INM3-700D480101	C4A i=5	250
1	IYJ4-45-89-16-ZP	45	36	4361	14. 4	148	16	2	27 57 89	INM2-630D240101	C4 i=7	210
0	1YJ4-50-92-18-ZP	50	36	4361	16	148	18	2 3	28 59 92	INM2-600D240101	C4 i=7	350
2	1YJ4-54-92-20-ZP	54	36	5428. 5	14. 0	182	20	2 3	(m) 27 57 89 27 57 89 28 59 92 28 59 92 33	INM3-10000480101	C4D i=5.5	390
3	IYJ4-60-111-20-ZP	60	32	6138	13. 7	183	20	2 3	71	INM4-1100D480101	C4D i=5.5	480
	IYJ4-62-111-20-ZP	62	32	5580	15. 6	167	20	2	111 33 71 111	INM4-11000480101	C4A i=5	480
	IYJ4-72-118-22-ZP	72	28	7238	14. 1	188	22	2 3	111 35 74 118	INM4-13000480101	C4D i=5.5	560
4	IYJ4-80-106-24-ZP	80	28	7238	15. 9	188	24	2 3	32 67 106	INM4-1300480101	C4D i=5.5	560

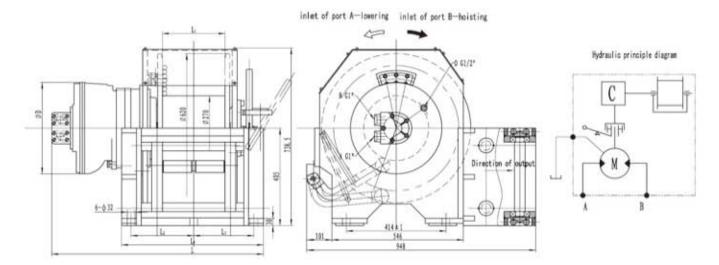
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Profile Dimension

	L1 (m)	Lz (m)	Li (m)	L (m)	0 (=
1	372	552	622	833	520
2	470	650	720	931	540
3	566	746	816	1046	560
4	650	830	900	1130	600

Distributors Model

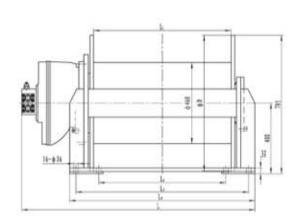
Supply oil flow(L/min)	Model	A	8
90-150	0240101	ф35	\$ 35
150-260	0480101	ф50	è 50

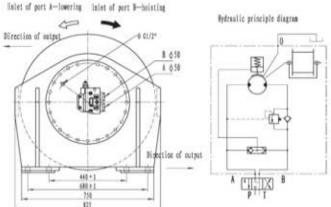


Basic	Model	The	1st layer	Total	Working	Supply oil flow	Diameter	Laure	Capacity	Hydraulic motor	Gearbox mod	al Weigh
node l	mode)	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	(MPa)	(L/min)	of rope (mm)	Layer	of rope (m)	riyuraulic moloi	Ocaroox moo	(kg)
1	IYJ4-40-134-16-L	40	13. 9	2429	18. 5	42	16	3 4 5 6	14 30 48 67 88 110	1NM2-350D47	C4 i=7	650
2	IYJ4-70-122-18-L	70	14. 8	3795	20.5	69	18	1 2 3 4 5 6	14 30 48 67 88 110 134 12 27 42 60 79 100 122	INN3-700D47	C4D i=5.5	670
1	IYJ4-100-126-20-L	100	14. 8	6138	18. 5	110	20	1 2 3 4 5	12 27 43 61 81 103 126	INM4-1100047	C4D i=5. 5	690

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	L1 (m)	L2 (m)	Ls (m)	Lt (m)	L (m)	D (m)
1	260	255	255	590	975	300
2	260	255	255	590	997	380
3	282	266	266	612	1038	410



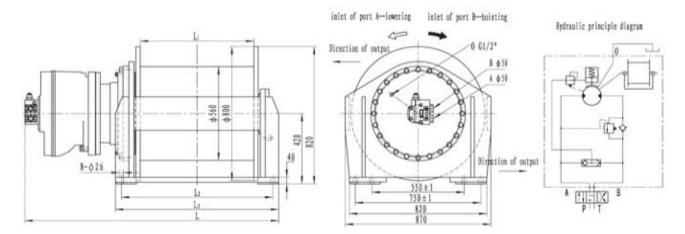


Basic	10000	The	e 1st layer	Total	Working	Supply	Diameter	Layer	Capacity	United to make	Gearbox	Wainh
model	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mm)	Layer	of rope (m)	Hydraulic motor	model	Weigh (kg)
	IYJ5-70-136-22-ZP	70	32	9212	13.6	216	22	2	30 64 101	INM4-1300480101	C5 i=7	800
1	IYJ5-80-110-24-ZP	80	32	9212	15. 8	216	24	2 3	101 28 59 94 35 74 116	INM4-1300D480101	C5 i=7	800
	IYJ5-90-158-24-ZP	90	33	11348	14. 4	256	24	2 3	35 74 116	INM5-1600D480101	C5 i=7	1050
2	IYJ5-95-148-26-ZP	95	34	11038.5	15. 6	256	26	2		INM5-2000D480101	C5D i=5.5	1050
	IYJ5-100-177-26-ZP	100	34	11038.5	16, 4	260	26	2 3	32 69 109 39 82 130	INM5-2000D480101	C5D i=5. 5	1100
3	IYJ5-110-177-26-ZP	110	32	11698. 5	17	260	26	1 2 3	39 82 130	INM6-2100D480101	C5D i=5.5	1100
	IYJ5-120-142-28-ZP	120	27	13821.5	15. 7	260	28	2 3	90 142	INM6-2500D480101	C5D i=5.5	1300
4	1YJ5-130-142-28-ZP	130	27	13821.5	17.0	260	28	1 2 3	42 90 142	INM6-2500D480101	C5D i=5. 5	1300

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Profile Dimension

ſ		Li (m)	L2 (m)	La (m)	L4 (m)	L (m)	D (m)
ľ	1	450	390	650	720	992	725
ľ	2	560	500	760	830	1193	750
ľ	3	670	610	870	940	1212	770
ľ	4	780	720	980	1050	1413	770

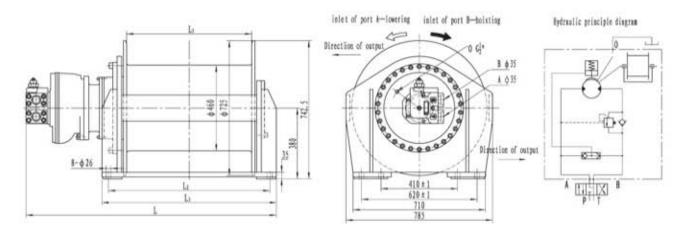


Basic	2000	The	1st layer	Total	Working	Supply	Diameter		Capacity	The second secon	Gearbox	Weight
model	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mm)	Layer	of rope	Hydraulic motor	model	(kg)
	IYJ6-100-127-26-ZP	100	34	14049	15. 6	280	26	2 3	38 81 127	INM5-2000D480101	C6 i=7	1200
-1	IYJ6-110-115-28-ZP	110	34	14049	17	280	28	2 3	38 81 127 35 74 115	INM5-2000D480101	C6 i=7	1200
	IYJ6-120-140-28-ZP	120	28	17591	15	280	28	1 2 3	93 140	INM6-2500D480101	C6 i=7	1450
2	IYJ6-125-135-30-ZP	125	28	17591	15. 7	280	30	1 2 3	41 86 135	INM6-2500D480101	C6 i=7	1450
	IYJ6-130-163-30-ZP	130	28	17591	16. 4	280	30	1 2 3	49 103 163	INM6-2500D480101	C6 i=7	1600
3	IYJ6-140-163-30-ZP	140	28	17591	17. 6	280	30	2 3	49 103 163	INM6-2500D480101	C6 i=7	1600
	IYJ6-145-198-30-ZP	145	29	16725.5	18. 9	280	30	1 2 3	61 129 204	INM6-3000D480101	C6D i=5. 5	1780
4	IYJ6-150-198-30-ZP	150	29	16725. 5	19. 6	280	30	1 2 3	61 129 204	INM6-3000D480101	C6D i=5. 5	1780

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Profile Dimension

	Litted	L2 (w)	Lt (m)	L (m)
1	550	776	846	1381
2	678	904	974	1509
3	800	1026	1096	1631
4	1000	1226	1296	1831

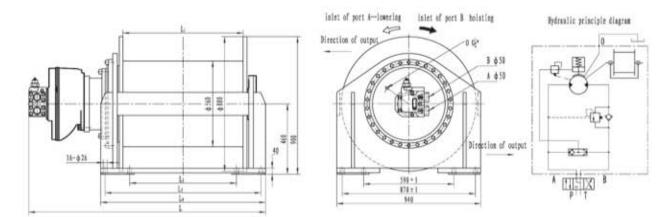


Basic	4.00	The	1st layer	Total	Working	Supply	Diameter	141	Capacity		Gearbox	Weight
model	Mode I	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mm)	Layer	of rope (m)	Hydraulic motor	model	(kg)
	IYJ45-100-111-26-ZP	100	19	13804	13. 5	180	26	2	33 70 111	INM2-5000240101	C45 i=28	960
1	IYJ45-110-111-26-ZP	110	19	13804	14.8	180	26	2 3	33 70 111	INM2-5000240101	C45 i=28	1050
	IYJ45-120-122-28-ZP	120	19	13804	16.3	180	28	2	33 70 111 33 70 111 36 77 122	INM2-5000240101	C45 i=28	1150
2	IYJ45-130-122-28-ZP	130	16	16660	14. 6	180	28	1 2 3	36 77 122	INM3-6000240101	C45 i=28	1120
	IYJ45-140-138-30-ZP	140	16	16660	15.8	180	30	2 3	41 87 138 41	INM3-6000240101	C45 i=28	1250
3	IYJ45-145-138-30-ZP	145	16	16660	16.3	180	30	2 3	41 87 138	INM3-600D240101	C45 i=28	1250
	IYJ45-150-163-32-ZP	150	14	19320	14. 6	180	32	2 3	48 102 163 48	INM3-700D240101	C45 i=28	1480
4	IYJ45-160-163-32-ZP	160	14	19320	15. 6	180	32	2 3	48 102 163	INM3-7000240101	C45 i=28	1480

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- 3. The winch is not designed for operation involving lifting or moving personnel.
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.

Profile Dimension

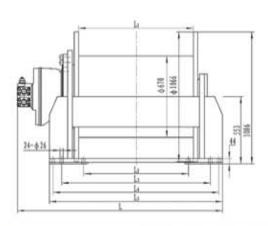
	Lt (m)	Lz (m)	Limi	L (m)
1	570	766	836	1262
2	671	865	935	1342
3	800	994	1064	1471
4	1000	1194	1264	1671

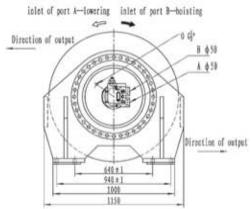


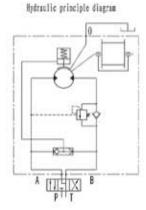
Basic	14000	The	1st layer	Total	Working	Supply	Diameter	Layer	Capacity		Gearbox	Weigh
mode l	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	III III OW OT TOPO	Layer	of rope (m) 48	Hydraulic motor	model	(kg)
	IYJ56-120-160-30-ZP	120	27	18080	15	280	30	2 3	48 102 160	INM4-900D480101P	C56 i=20	1450
1	IYJ56-130-160-30-ZP	130	27	18080	16. 2	280	30	2 3	48 102 160 55	INM4-900D480101P	C56 i=20	1450
	IYJ56-140-183-30-ZP	140	24	20440	15. 5	280	30	2 3	55 116 183 55	INM4-10000480101P	C56 i=20	1450
2	IYJ56-150-183-30-ZP	150	24	20440	16. 6	280	30	2 3	55 116 183 56	INM4-10000480101P	C56 i=20	1450
	IYJ56-160-188-32-ZP	160	21	23700	15. 2	280	32	2 3	119	INM5-12000480101P	C56 i=20	1650
3	IYJ56-170-188-32-ZP	170	21	23700	16. 1	280	32	2	56 119 188	INM5-12000480101P	C56 i=20	1650
	IYJ56-180-196-34-ZP	180	18	26800	15. 3	280	34	2	59 124 196 56	INM5-13000480101P	C56 i=20	1750
4	IYJ56-200-187-36-ZP	200	18	26800	17	280	36	2	56 118 187	INM5-13000480101P	C56 i=20	1750

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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.

	L1 (w)	L2 (m)	Lt (m)	Limit	L (m)
1	786	698	1018	1078	1547
2	900	812	1132	1192	1661
3	1000	912	1232	1292	1761
4	1100	1012	1332	1392	1805



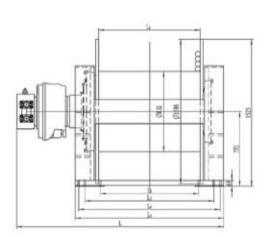


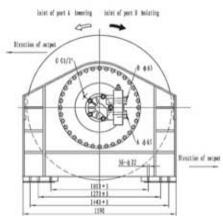


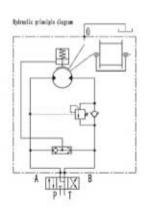
Basic	- W01/2	The	1st layer	Total	Working	Supply	Diameter	Layer	Capacity		Gearbox	Weight
mode l	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mm)	Layer	or rope (m)	Hydraulic motor	model	(kg)
3	IYJ67-150-211-32-ZP	150	20	29092	13. 9	280	32	2 3	64 134 211	INM5-1000D480101	C67 i=28	2000
2	IYJ67-160-211-32-ZP	160	20	29092	14. 8	280	32	2 3	64 134 211	INM5-1000D480101	C67 i=28	2000
	IYJ67-180-224-36-ZP	180	18	33180	14.7	280	36	2 3	67 142 224	INM5-1200D480101	C67 i=28	2220
2	IYJ67-200-224-36-ZP	200	18	33180	16. 3	280	36	2 3	67 142 224	INM5-1200D480101	C67 i=20	2220
	IYJ67-250-232-40-ZP	250	13	45752	14. 8	280	40	2 3	69 147 232	INM5-1600D480101	C67 i=28	2390
	IYJ67-280-232-40-ZP	280	13	45750	16. 6	280	40	2 3	69 147 232	INM5-1600D480101	C67 i=28	2390
3	IYJ67-300-214-44-ZP	300	12	50848	16. 1	280	44	1 2 3	63 135 214	INM5-1800D480101	C67 i=28	2450
	IYJ67-320-214-44-ZP	320	12	50848	17. 2	280	44	2	63 135 214	INM5-1800D480101	C67 i=28	2450

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.

	Li (m)	L2 (m)	Li (w)	Limit	Ls (m)	L (m)
-1	936	855	1215	1355	1415	1679
2	1100	1019	1379	1519	1579	1843
3	1250	1169	1529	1669	1729	1993



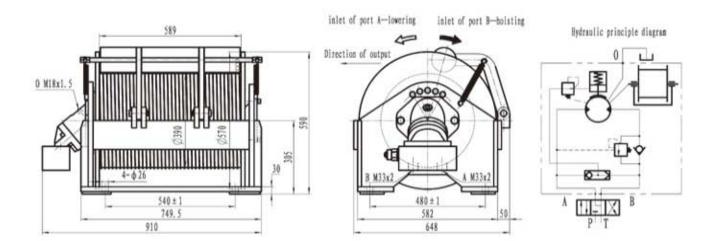




		The	1st layer	Total	Working	Supply	Diameter	Layer	Capacity	100 W W E	Gearbox	Weight
Basic model	Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	Marie Contraction		of rope	Hydraulic motor	model	(kg)
	IYJ79-300-253-46-ZP	300	16.8	70728	14	480	46	1 2 3 4	55 115 181 253	INM7-2500D720101	C79 i=28	3500
	IYJ79-400-253-46-ZP	400	16.8	83580	16	480	46	2 3 4	(m) 555 115 181 253 55 115 181 253 55 117	I NM7-3000D720101	01 C79 i=28	3500
	IYJ79-500-261-52-ZP	500	10	120344	14	480	52	2 3 4	55 117 186 261	INM7-4300D720101	C67 i=28	4000
2	IYJ79-550-261-52-ZP	550	10	120344	15. 5	480	52	2 3 4	186 261 55 117 186 261	I NM7-4300D720101	C67 i=28	4000

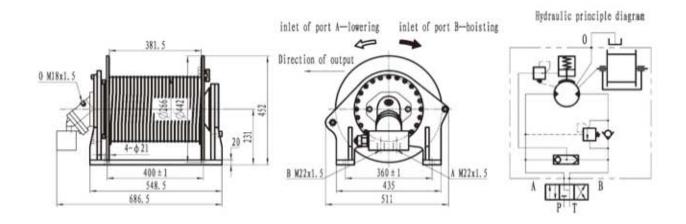
- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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	£1 (m)	1200	Lo (m)	La Good	L5 (m)	E (m)
1	895	860	1190	1320	1390	1897
2	1065	1020	1350	1480	1550	2057



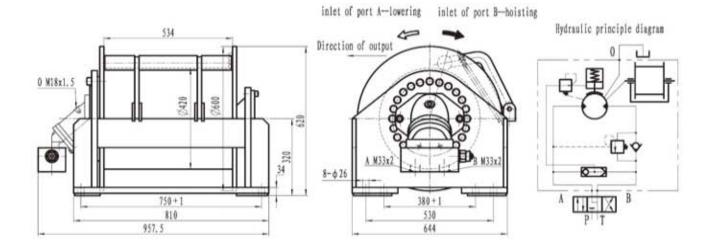
	1	The 1st layer	Total	Working	Supply	Diameter	la mana di	Canacity	Hydraulic	Gearbox	Weigh
Mode I	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)		of rope	Layer	of rope	motor	model	(kg)
		50000	E 24/2/2 (4/2/2)	200000	(Nesco)	5-00	1	46	STORES NO.	IGC17W2	-
1YJ33-20-164-14-ZPG	20	100	1486. 7	20. 8	130	14	2	103	A2FE56		920
	1			00000		10.300	3	164	O processors.	i=26.5	
							1	46		1001780	
IYJ33-25-164-14-ZPG	25	100	1486. 7	26. 1	130	14	2	103	A2FE56	IGC17W2 i=26.5	920
	1000	100000				2.5462	3	164			
							1	39		1001780	
1YJ33-30-144-16-ZPG	30	74	2103.8	22. 2	130	16	2	90	A2FE56	IGC17W2	920
						11.0	3	144		i=37. 2	
							1	39		1001780	
1YJ33-35-144-16-ZPG	35	74	2103.8	26. 6	130	16	2	90	A2FE56	IGC17W2	920
							3	144		1=37.5	
							1	39			
IYJ33-40-144-16-ZPG	33-40-144-16-ZPG 40	40 68 2362.5	5 27.0	140	140 16	2	90	A2FE63	E63 IGC17W2	920	
	1.0		2302. 5	21.0			3	144		i=37.5	

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - 3. The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
 - 5. This hydraulic winch series can driven by A6V variable displacement motor.



	Th	ne 1st layer	Total	Working	Supply	Diameter of rope		Capacity	Hydraulic	Gearbox	Weigh
Mode I	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow	of rope	Layer	of rope		model	(kg)
					- Inches		1	17		IGC17W3	
IYJ333-35-65-16-ZPG	35	35	1618. 2	22. 9	73	16	2	40	A2FE32	1241374818181	750
							3	65		i=50. 57	
							1	17		IGC17W3 i=50.57	
1YJ333-40-65-16-ZPG	40	35	1618. 2	26. 2	73	16	2	40	A2FE32		750
	11.5	57.75			1013	0.75	3	65	Constitution of		47.5
						21-1	1	17		IGC17W3	
IYJ333-45-65-16-ZPG	45	35	1618. 2	29. 4	73	16	2	40	A2FE32	10,000,000,000	750
	1,075	1000			503800	700	3	65	460000000	i=50. 57	10000
							1	17		1001789	
IYJ333-50-65-16-ZPG	50	35	2306.0	23. 4	101	16	2	40	A2FE45	IGC17W3	750
				77.00		.717.0	3	65		' i=50. 57	
							1	17		15 IGC17W3	
IYJ333-55-65-16-ZPG	55	35	2306. 0	25. 8	101	16	2	40	A2FE45		750
							3	65		i=50. 57	

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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. This hydraulic winch series can driven by A6V variable displacement motor.



Model	Pull (KN)	The 1st layer Rope speed (m/min)	1,700	Working pressure diff. (MPa)	Supply oil flow (L/min)	Diameter of rope (mm)	l aver	Capacity of rope (m)	Hydraulic motor	Gearbox model	Weigh
		100.001.000	- July 1. Sty	Visit Service		1007	1	37	V000-000	IGC36W3	
IYJ344-60-178-18-ZPG	60	54	3807. 5	27.1	160	18	2	81	A2FE56	i=67. 87	960
110044 00 170 10 274	00	34	3007. 3	21.1	100	10	3	129		1-07.07	
							4	178			
							1	33		IGC36W3	
IYJ344-70-117-20-ZPG	70	47	4403. 9	27. 5	160	20	2	74	A2FE56		960
							3	117		i=78.50	
							1	33		IGC36W3 i=78.50	
1YJ344-80-117-20-ZPG	80	37	5559.5	25	160	20	2	74	07FF56		ukn
							3	117			
							1	30		1GC36W3	
1YJ344-90-108-22-ZPG	90	38	5559. 5	28. 1	160	22	2	67	A2FE56		960
							3	108		i=99.10	
		200			2 0230211		1	28		1GC36W3	
IYJ344-100-100-24-ZPG	100	29	7281	24	160	24	2	62	A2FE56		960
	1000	222		357.5		2500	3	100		i=99. 10	120000
			1100000				1	28		1002682	
IYJ344-110-100-24-ZPG	110	29	7281	26.5	160	24	2	62	A2FE56	1=99. 10	960
	0.000	(2.70)		11000000		1.000	3	100			Alexander
							1	28			
IYJ344-120-100-24-ZPG	120	29	7281	28. 6	160	24	2	62	A2FE56		960
	1	17.51	.2004.0	1.25540.24	1.350.76	000.0	3	100	nevanosas.		300

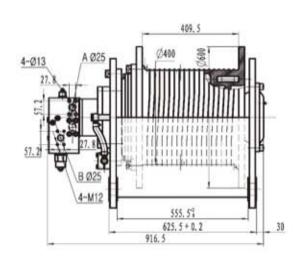
- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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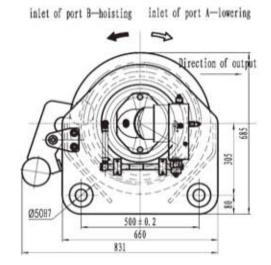
inlet of port A-lowering inlet of port B-hoisting

422	Direction of out at	Hydraulic principle diagram
0 M18x1.5		
		Ö
	B M33x2 A M33x2	□ ◊
16-\$26	485 ± 1 745	A B
700 770 960.3	815	r 1

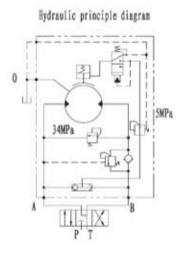
	Th	e 1st layer	Total	Working	Supply	Diameter		Capacity	Hydraulic	Gearhov	Weigh	
Model	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)			aver	of rope		model	(kg)	
	040	OW MITH	ymi/rev)	(Mrd)	(Cristily	Unity	1	22			(ng/	
IYJ455-100-115-26-ZPG	100	41	7638	25. 4	210	26	2	51	A2FE80	IGC60W3	1300	
	100	10.75	7000	20. 1	2.5	100	3	82	1.2.	i=95	10000	
						- 0	4	115				
							1	22		LOOCOWO		
IYJ455-110-115-26-ZPG	110	41	7638	27. 9	210	26	2	51	A2FE80	IGC60W3	1300	
							3	82		i=95		
							4	115				
							1	22		10000000		
IYJ455-120-115-26-ZPG	120	34	9181.7	25. 4	210	26	2	51	A2FE80	IGC60W3	1300	
	1.5	177	313111	57707	200		3	82		i=114.2	31000	
						- 6	4	115				
							1	21			LOCOCOMO	
IYJ455-130-108-28-ZPG	130	34	9181.7	27. 6	210	28	2	47	A2FE80	IGC60W3	1300	
110100 100 100 20 21 0	100		010111	27.0	2.0		3	77	TIET EUG	i=114.2	1000	
							4	108				
							1	21		100455		
IYJ455-140-108-28-ZPG	140	30	10725.4	25. 4	210	28	2	47	A2FE80	1GC455	1300	
	1.0				2.0		3	77	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	i=133.4		
						1	4	108	1			
							1	21		100455		
1YJ455-150-108-28-ZPG	150	30	10725.4	27. 2	210	28	2	47	A2FE80	1GC455	1300	
	100		1076071	2112		2.0	3	77		i=133.4	1000	
							4	108				

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. This hydraulic winch series can driven by A6V variable displacement motor.

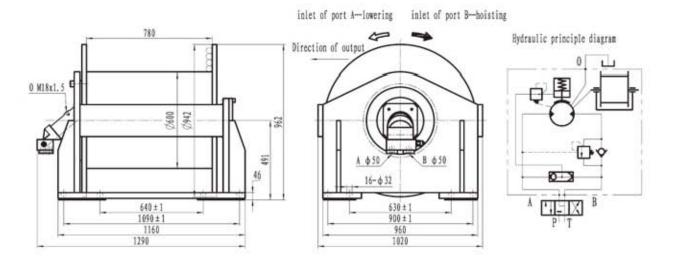




Mode I	IYJ455-10)2-82-20-Z	PG		
Pull on the 3rd layer(kN)		102			
Speed on the 1st layer(m/min)		42	42 3134. 4 32 220 20		
Total displacement (ml/r)		6134.4			
Work pressure diff. (MPa)		32			
Supply oil flow(L/min)		220			
Diameter of rope(mm)		20			
layer	1	2	3		
Capacity of rope(m)	25	52	82		
Hydraulic motor	A2FE80	/6. 1WVZL1	0		
Gearbox model	1GC60/	N3 i=76.68			

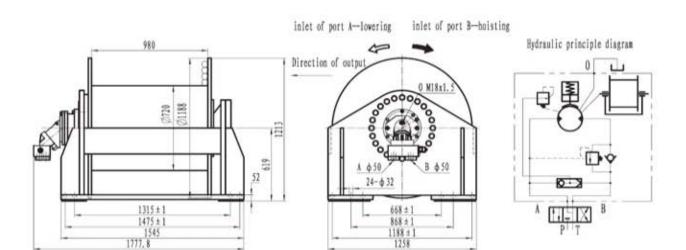


- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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- 5. This hydraulic winch series can driven by A6V variable displacement motor.
- 6. If the winch requires pressing rope by gravity, the winch should be turned 90° when installation, otherwise the rope-roller is invalid.



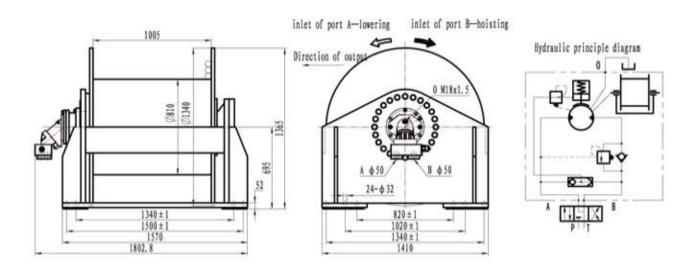
	T	he 1st layer	Total	Working	Supply	Diameter	0	Capacity	Hydraulic	Gearbox	Weigh
Model	Pull	Rope speed	displacement	pressure diff.	oil flow	of rope	Layer	of rope	motor	model	vveign
	(KN)	(m/min)	(ml/rev)	(MPa)	(L/min)	(mm)		(m)			(kg)
	10,700	1 100	- PATRICINA	175 SUL	-0.000	2122	1	55	100 AK 40 DEC	1GC80W3	-01000
IYJ466-150-256-26-ZPG	150	50	13425. 5	26. 9	363	26	2	119	A2FE160		1700
	The same		AVIOLATIA I				3	188	The state of the s	i=83. 7	100110700
							4	256			
							1	51		1GC80W3	
IYJ466-160-241-28-ZPG	160	50	13425.5	28. 7	363	28	2	111	A2FE160	i=83. 7	1/00
							3	176		1-83. /	
							4	241			
			11.00.000.000.00	NAME OF THE OWNER, OF THE OWNER, OF THE OWNER,			-1	48		1GC80W3	
IYJ466-170-228-30-ZPG	170	43	15799.4	26.0	363	30	2	104	A2FE160	1	1700
			A.500.00				3	166		i=98.5	
						1	4	228			
							1	45		1GC80W3	
IYJ466-180-216-32-ZPG	180	43	15799. 4	27. 6	363	32	2	98	A2FE160	i=98.5	1700
						1	3	156		1-95. 3	
							4	216		1GC80W3	
							1	42			
IYJ466-200-200-34-ZPG	-200-200-34-ZPG 200	200 37 18205. 4	5. 4 26. 7	363	363 34	3 34	2	93	A2FE160	100000000000000000000000000000000000000	1700
								3	148		i=113.5
							4	200			

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. This hydraulic winch series can driven by A6V variable displacement motor.



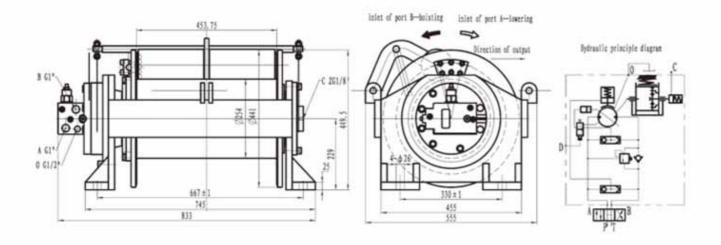
	Tr	ne 1st layer	Total	Working	Supply	Diameter	- med	Capacity	Hydraulic	Gearbox	Weigh
Mode I	Pull (KN)	Rope speed (n/min)	displacement (ml/rev)	pressure diff.	oil flow (L/min)	of rope (mm)	Layer	of rope (m)	motor	model	(kg)
	resocue	2000	SANCESCA CO.	2.14.470 1.0008768		10000	1	65	CVOTA STANDARS	IGC160W3	YOURSE
IYJ477-200-300-34-ZPG	200	34	25952. 7	22.7	400	34	2	139	A2FE125	i=161.8	2600
					222		3	220		1-101.0	
							4	300			
					10.000000		1	61		IGC160W3	
1YJ477-250-280-36-ZPG	250	35	25952. 7	28. 4	400	36	2	132	A2FE125	100000000000000000000000000000000000000	2600
	1 272				~~		3	209		1=101.8	100000
							4	280			
		1000	200000000000000000000000000000000000000	50mm/s 5005	S 2000		1	58			
IYJ477-300-270-38-ZPG	300	26	33812.3	26. 3	400	38	2	125	A2FE125		2600
	10000	3.545		0.000	197.078		3	199			73300
							4	270			
	lane.						1	55		IGC160W3	
1YJ477-320-260-40-ZPG	320	27	33812.3	27. 6	400	40	2	120	A2FE160	100000000000000000000000000000000000000	2600
	1	17038					3	190		i=210.8	Care
							4	260		E160 IGC160W3	
		19-57	Constitution to a financial constitution of the constitution of th	or the property of	v 2000		1	52			
1YJ477-350-250-42-ZPG	350	27	33812.3	30.8	400	42	2	114	A2FE160		2600
	28.5107	(5%			A5743		3	183			03976
							4	250			

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- 3. The winch is not designed for operation involving lifting or moving
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. This hydraulic winch series can driven by A6V variable displacement motor.



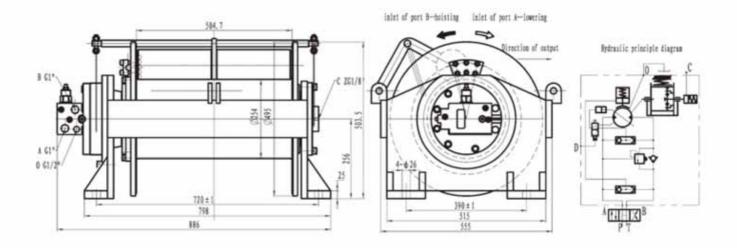
	TI	ne 1st layer	Total	Working	Supply	Diameter		Capacity	Hydraulic	Gearbox	Weigh
Mode I	Pull (KN)	Rope speed (m/min)	displacement (ml/rev)	77.00	oil flow (L/min)	of rope	Layer	of rope	motor	model	(kg)
	Unity	QIQ III TIQ	Unit/164)	(Mr a)	(Criminy)	frest	1	58		100000000	
IYJ488-350-199-44-ZPG	350	21.5	46997. 2	24. 8	400	44	2	125	A2FE160	1GC220W3	3200
							3	199		i=245. 9	
							1	55		1GC220W3	
IYJ488-400-192-46-ZPG	400	22	46997. 2	28. 1	400	46	2	120	A2FE160	i=293.0	3200
							3	192		1-293.0	
				16-100-1-1-			1	53		1GC220W3	
IYJ488-450-185-48-ZPG	450	22	52740.0	28. 1	450	48	2	116	A2FE180	i=293.0	3200
							3	185		1-293. 0	
							1	51		1GC220W3	
IYJ488-480-178-50-ZPG	480	20	56340.0	28. 1	450	50	2	111	A2FE180	i=313.0	3200
							3	178		1-313.0	
		.1705	SoleVel Septime	02 90 W 100	100707.1		1	51		1GC220W3	
IYJ488-500-178-50-ZPG	500	20	56340.0	29.3	450	50	2	111	A2FE180	i=313.0	3200
							3	178		1-313.0	

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- 5. This hydraulic winch series can driven by A6V variable displacement motor.



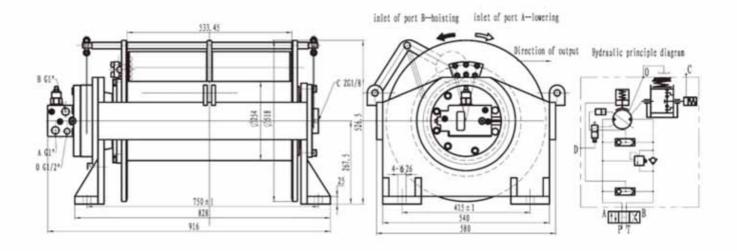
	The	1st layer	Total	Working	Supply	Diameter		Capacity	and the same				
Model	Pull (XX)	Rope speed (m/min)	displacement (ml/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mn)	Layer		Hydraulic motor	Gearbox			
										1	23		
		SCORE LANCE					2	48		1GC26W2			
YJ33-25/12. 5-142-16-ZPGL	25/12.5	50/100	1909. 2/954. 6	16.7	119	16	3	76	1M86/43				
							4	108		i=22. 2			
							5	142					
							1	23					
							2	48		1GC26W2 i=22.2			
1YJ33-30/15-142-16-ZPGL	30/15	50/100	1909. 2/954. 6	6 20	119 16	9 16	3	76	1M86/43				
						4	108		1-22.2				
							5	142					
							1	23					
							2	48		1GC26W2			
YJ33-35/17. 5-142-16-ZPGL	35/17.5	50/100	1909. 2/954. 6	23.3	119	16	3	76	1M86/43				
							4	108		i=22. 2			
							5	142					
							1	23					
							2	48		1GC26W2			
IYJ33-40/20-142-16-ZPGL	40/20	50/100	1909. 2/954. 6	26	119	16	3	76	1M86/43				
				4	108		i=22.2						
							5	142					

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- 6. Clutch is switched on and off by pneumatic control. The gas pressure at port C is allowed to be 5-7bar. The control valve is provided by user self.



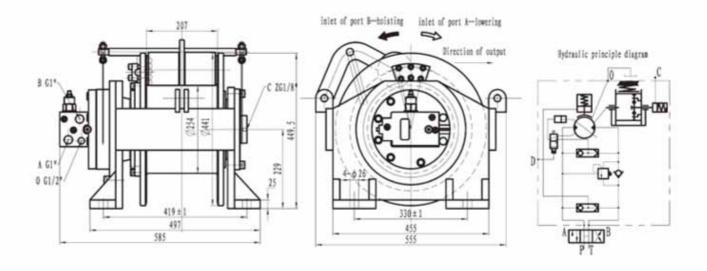
	The	1st layer	Total	Working	Supply	Diameter		Capacity	Hallerin		
Wodel	Pull (XXX)	Rope speed (m/min)	displacement (n1/rev)	pressure diff. (MPa)	oil flow (L/min)	of rope (mm)	Layer	of rope	Hydraulic motor	Gearbox	
	-	44,010	9017,4,942				1	20		II CONTRACTOR OF THE PARTY OF T	
							2	44		1GC26#	
IYJ33-50/25-133-20-ZPGL	50/25	30/60	3182/1591	16.7	119	20	3	71	1886/43		
							4	100		i=37	
							5	133		11.147	
							1	20			
							2	44		16C26W	
IYJ33-60/30-133-20-ZPGL	60/30	30/60	3182/1591	20	119	20	3	71	1M86/43		
								4	100		i=37
							5	133			
							1	20			
							2	44		IGC26W	
IYJ33-70/35-133-20-ZPGL	70/35	30/60	3182/1591	23.3	119	20	3	71	1M86/43		
							4	100		i=37	
							5	133			
							1	20			
							2	44		1GC26W	
IYJ33-80/40-133-20-ZPGL	80/40	30/60	3182/1591	26. 7	119	20	3	71	IM86/43		
							4	100		i=37	
							5	133		10000000	

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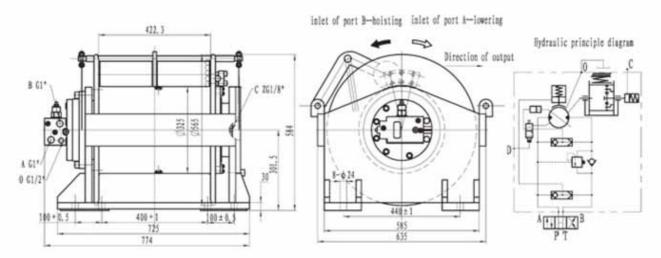
	The	e 1st layer	Total	Working	Supply	Diameter		Canacity	Hydraulic	Gearbox
Model	Pull	Rope speed	displacement	pressure diff.	oil flow	of rope	Layer	of rope		model
	000	(n/min)	(ml/rev)	(MPa)	(L/min)	(m)		(n)		
							_1	20		
							2	43		1GC26W3
YJ333-80/40-131-22-ZPGL	80/40	20/40	4538. 22/2269. 11	17.8	119	22	3	69	IM86/43	i=52.77
							4	99		1-02. 11
							5	131		
							1	20		
						2	20 43 69		1GC26W3	
YJ333-90/45-131-22-ZPGL	90/45	20/40	4538. 22/2269. 11	20	119	22	3		1M86/43	i=52.77
							4	99		1-02.11
							5	131		
							1	20 43		
							2	43		1GC26W3
YJ333-100/50-131-22-ZPGL	100/50	20/40	4538, 22/2269, 11	22.2 119 22	11 22.2 119 22		69	1M86/43		
		73001130		2127.27			4	99		i=52.77
							5	131		

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - 3. The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
 - 5. The operation of switch off clutch must be carried out under stop of the winch. The operation of switch on clutch should be done without load on drum and put the latch of clutch in proper position when working.
 - 6. Clutch is switched on and off by pneumatic control. The gas pressure at port C is allowed to be 5-7bar. The control valve is provided by user self.



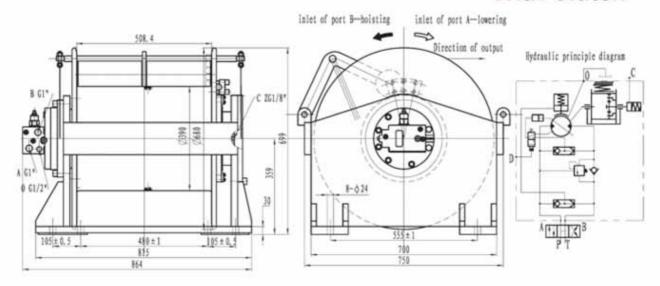
Model	IYJ333-90/45-63-16-ZPGL						
Pull on the 1st layer(kN)		90			j		
Speed on the 1st layer(m/min)		20		40			
Total displacement(ml/r)	45	38. 22		2269	.11		
Work pressure diff. (MPa)	20						
Supply oil flow(L/min)	119						
Diameter of rope(mm)			16				
layer	1	2	3	4	5		
Capacity of rope(m)	10	21	34	48	63		
Hydraulic motor	1M86/43						
Gearbox model	IGC26 i=52.77						

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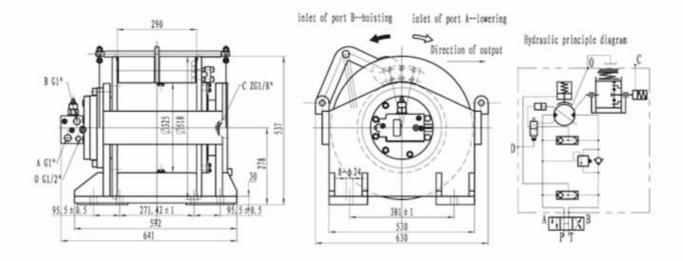
	The	1st layer	Total	Working	Supply	Diameter		Capacity	Hydraulic	Gearbox
Mode I	Pull	Rope speed	displacement	pressure diff.	oil flow	of rope	Layer	of rope	motor	model
	000	(n/min)	(ml/rev)	(MPa)	(L/min)	(mn)		(n)		
							1	21		
							2	45		1GC36W3
IYJ444-60/30-133-20-ZPGL	60/30	29/58	4558/2279	18	130	20	3	72	1M86/43	
	10000	i managa	0.6000000000000000000000000000000000000		157.55		4	102	10001-00	i=53
							5	133		
							1	21		
							2	45		1GC36W3
IYJ444-70/35-133-20-ZPGL	70/35	29/58	4558/2279	21.1	130	20	3	72	1M86/43	
							4	102		i=53
							5	133		
							-1	21		
							2	45	IM86/43	1GC36#3
IYJ444-80/40-133-20-ZPGL	60/30	29/58	4558/2279	24.1	130	20	3	72		
	-01010		- 17/0/09/2012		19878		4	102		i=53
							5	133		
							1	21		
							2	45	US TO STORE	1GC36W3
IYJ444-90/45-133-20-ZPGL	60/30	29/58	4558/2279	27.1	130	20	3	72	1M86/43	
							4	102		i=53
							5	133		
							1	21		
							2	45		1GC36W3
YJ444-100/50-133-20-ZPGL	PGL 60/30 29/58 4558/2279 30 130			130 20	IM86/43					
	100.000	STATUTE A			3,53,50		4	102		i=53
							5	133		

- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
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	The	1st layer	Total	Working	Supply	Diameter		Capacity	Hydraulic (Gearbox				
Model	Pull	Rope speed	displacement	pressure diff.	oil flow	of rope	Layer	of rope		model				
	(XX)	(n/min)	(ml/rev)	(MPa)	(L/min)	(m)		(m)						
			100,000				1	26						
						3	55		1GC36W3					
YJ444-110/55-160-24-ZPGL	110/55	19/38	8522. 6/4261. 3	21	130	24		87	IM86/43	i=99.1				
						4	122		1-99. 1					
							5	160						
											1	26		
							2	55		1GC36W3				
YJ444-120/60-160-24-ZPGL	120/60	19/38	8522. 6/4261. 3	23 1	23	130	130 24 3 4	3	87	IM86/43	i=99.1			
						177.02		122		1-33. 1				
							5	160						
							1	26		16C36W3				
					CAAC 221	221	2	55						
YJ444-130/65-160-24-ZPGL	130/65	19/38	8522. 6/4261. 3	24.7	24.7	24.7	130 24	24	3	87	IM86/43	i=99.1		
								122	5	1.00.				
							5	160						
							1	26						
V 1444 140/70 100 04 7001	140.770	10/00	0500 0 (4004 0	00.0	100	0.4	3 4	55 87	1900740	16036W				
YJ444-140/70-160-24-ZPGL	140/10	19/38	8522. 6/4261. 3	1.3 26.6	130	24	3	122	1M86/43	i=99.1				
							5	160						
							1	26						
	L150/75 19/38 8522.6/4261.3 28.5 130						2	55		72398833				
YJ444-150/75-160-24-ZPGL		9522 6/4261 2	8 8522.6/4261.3 28.5 130 24	9522 6/4261 3 29 5 130	9522 6/4261 3	/20 0522 6/4261 2 20 6 15	5 120	120 24	130 24	120 24	3	87	1M86/43	16036W3
10444 100/10-100-24-2FGL	130/10	J/ 13 13/30 0322. 0/4201. 3 20. 3 130 24		122	1800/43	i=99.1								
							5	160						

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- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. The operation of switch off clutch must be carried out under stop of the winch. The operation of switch on clutch should be done without load on drum and put the latch of clutch in proper position when working.
- 6. Clutch is switched on and off by pneumatic control. The gas pressure at port C is allowed to be 5-7bar. The control valve is provided by user self.



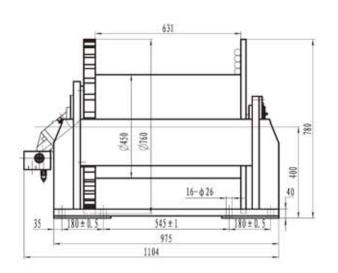
1YJ444-150/75-71-20-ZPGL				
Pull on the 1st layer(kN)		150	7	5
Speed on the 1st layer(m/min)	- 3	2.2	24	. 4
Total displacement(ml/r)	(9560	47	180
Work pressure diff. (MPa)			21	
Supply oil flow(L/min)			120	
Diameter of rope (mm)			20	
layer	1	2	3	4
Capacity of rope(m)	15	32	50	71
Hydraulic motor		1M8	6/43	
Gearbox model		16C36	i=111.	2

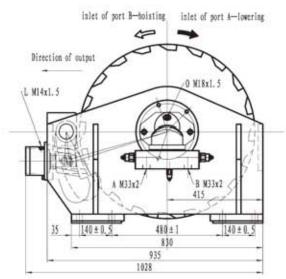
Note: 1. Total displacement represents the capacity of oil supply pre revolution.

- 2. Flow of oil supply indicates theoretical flow of pump when the volumetric efficiency considered as 90 percent.
- 3. Capacity of rope is theoretical capacity of rope. The practical available capacity of rope should subtract the retained 3m wire in case of rope head is out of hand.
- 4. Working pressure difference represents the pressure drop between Port A and Port B.
- The winch is not designed for operations involving lifting or moving personnel.
 The operation of switch off clutch must be carried out under stop of the winch. The operation of switch on clutch should be done without load on drum and put the latch of clutch in proper position when working.
- 7. Clutch is switched on and off by pneumatic control. The gas pressure at port C is allowed to be 5-7bar. The control valve is provided by user self.

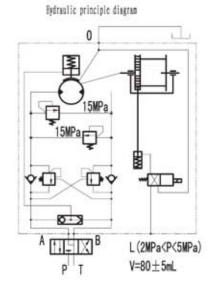


IYJ344-50-167-26-ZPGS Hydraulic Winch





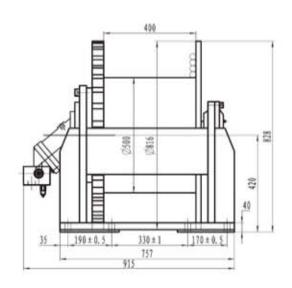
Model	1YJ344	-50-167	-26-ZPG	3		
Pull on the 4th layer(kN)		5)			
Support pull(kN)		17	0			
Speed (m/min)		7.	4			
Total displacement(ml/r)	9949. 15					
Work pressure diff. (MPa)	13					
Supply oil flow(L/min)		4	8			
Diameter of rope(mm)		2	6			
layer	1	2	3	4		
Capacity of rope(m)	35	75	119	167		
Hydraulic motor	A2FE56/6. 1WVAL10					
Gearbox model	IGC36 i=177.35					

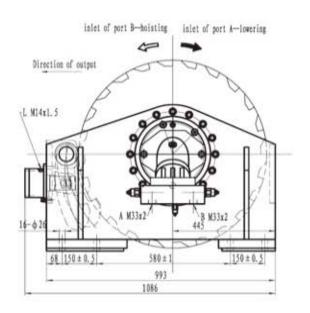


- 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- 3. The winch is not designed for operation involving lifting or moving personnel.
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
- 5. This hydraulic winch series can driven by A6V variable displacement motor.

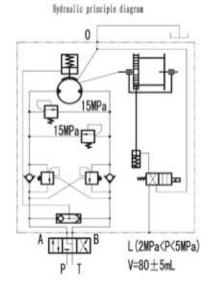


IYJ455-130-113-26-ZPGS Hydraulic Winch





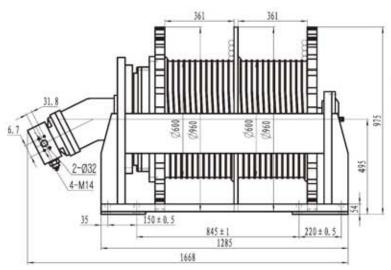
Model	17,14	55-130-	113-26-	ZPGS	
Pull on the 4th layer(kN)		13	0		
Speed (m/min)		6			
Total displacement(ml/r)		1660	2. 5		
Work pressure diff. (MPa)		2	1		
Supply oil flow(L/min)	58				
Diameter of rope (mm)		26	3		
layer	1	2	3	4	
Capacity of rope(m)	24	52	81	113	
Hydraulic motor	A2FE107/6. 1WVZL10				
Gearbox model	IGC60 i=155.6				

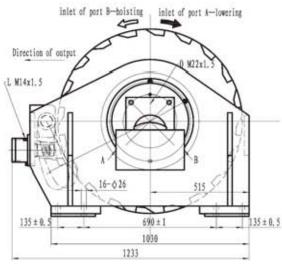


- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - 3. The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
 - 5. This hydraulic winch series can driven by A6V variable displacement motor.



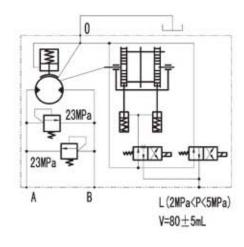
IYJ477-153x2-107x2-28-ZPGS Hydraulic Winch





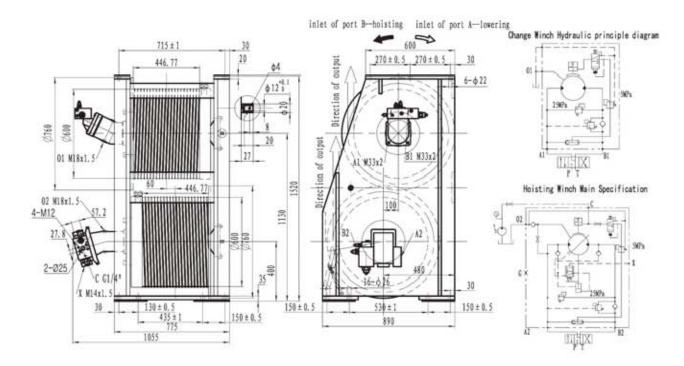
Hydraulic principle diagram

Mode I	1YJ477-153x2-107x2-28-Z					
Pull on the 4th layer(kN)		153	x2			
Speed (m/min)		10)			
Total displacement(ml/r)		462	50			
Work pressure diff. (MPa)	21					
Supply oil flow(L/min)	220					
Diameter of rope(mm)		28	3			
layer	1	2	3	4		
Capacity of rope(m)	23	49	77	107		
Hydraulic motor	A2F250W5Z1					
Gearbox model	IGC160 i=185					



- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - 2. The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - 3. The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.
 - 5. This hydraulic winch series can driven by A6V variable displacement motor.





Hoisting Winch Hydraulic principle diagram

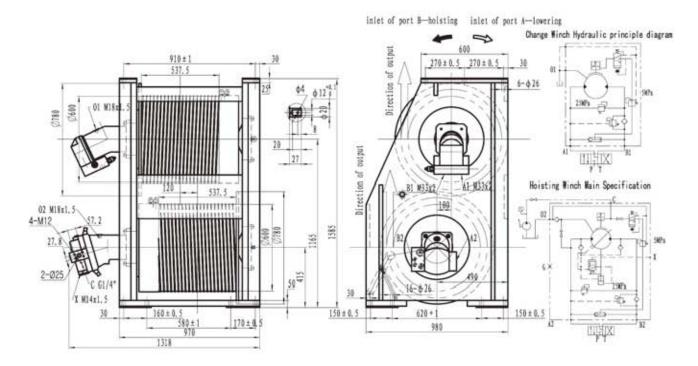
Mode I	IYJ344-58-	84-20-ZPG
Pull on the 2nd layer(kN)	57. 5	15
Speed on the 1st layer(m/min)	33	68
Work pressure diff. (MPa)	23	14
Supply oil flow(L/min)	121	
Diameter of rope(mm)	20	
layer	1	2
Capacity of rope(m)	40	84

Change Winch Main Specification

Model	1YJ344-58-84-20-ZPG	
Pull on the 2nd layer(kN)	57. 5	
Speed on the 1st layer(m/min)	33	
Work pressure diff. (MPa)	23	
Supply oil flow(L/min)	121	
Diameter of rope(mm)	20	
layer	1	2
Capacity of rope(m)	40	84

- The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- The winch is not designed for operation involving lifting or moving personnel.
- When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

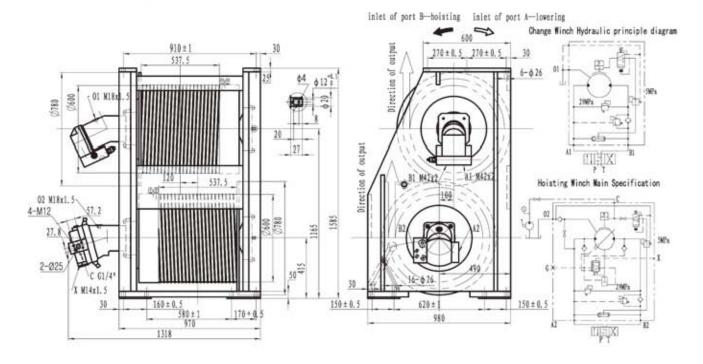
Model	1YJ344-86-84-24-ZPG	
Pull on the 2nd layer(kN)	86.3 30	
Speed on the 1st layer(m/min)	33	68
Work pressure diff. (MPa)	24	17
Supply oil flow(L/min)	163	
Diameter of rope(mm)	24	
layer	1	2
Capacity of rope(m)	40	84

Change Winch Main Specification

Model	1YJ344-86-84-24-ZPG	
Pull on the 2nd layer(kN)	86. 3	
Speed on the 1st layer(m/min)	33	
Work pressure diff. (MPa)	24	
Supply oil flow(L/min)	163	
Diameter of rope(mm)	24	
layer	1	2
Capacity of rope(m)	40	84

- The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- The winch is not designed for operation involving lifting or moving personnel.
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

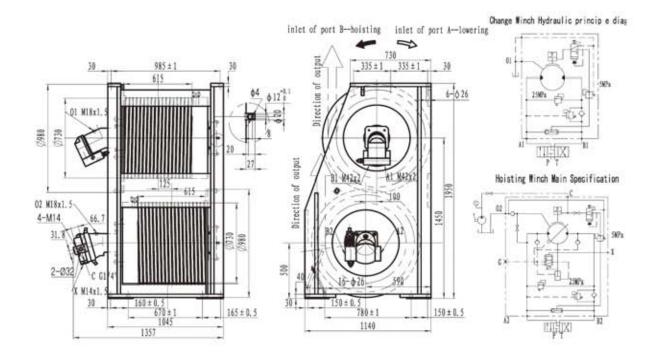
Model	1YJ455-115-84-24-ZPG	
Pull on the 2nd layer(kN)	115	40
Speed on the 1st layer(m/min)	39	72
Work pressure diff. (MPa)	27	19
Supply oil flow(L/min)	248	
Diameter of rope(mm)	24	
layer	1	2
Capacity of rope(m)	40	84

Change Winch Main Specification

Model	1YJ455-115-84-24-ZPG	
Pull on the 2nd layer(kN)	115	
Speed on the 1st layer(m/min)	39	
Work pressure diff. (MPa)	27	
Supply oil flow(L/min)	248	
Diameter of rope(mm)	24	
layer	1	2
Capacity of rope(m)	40	84

- The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
- The winch is not designed for operation involving lifting or moving personnel.
- 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

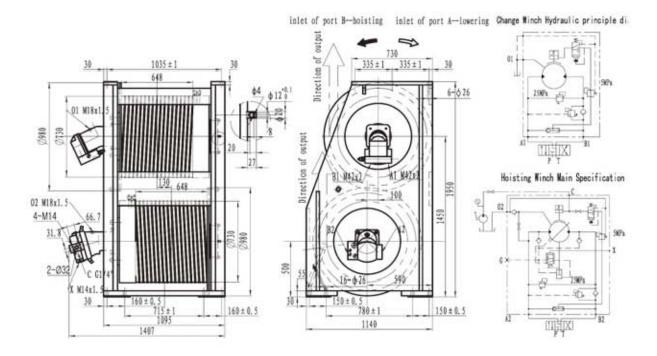
Mode I	IYJ466-138-90-32-ZP0	
Pull on the 2nd layer(kN)	138	27. 6
Speed on the 1st layer(m/min)	30	60
Work pressure diff. (MPa)	23	23
Supply oil flow(L/min)	273	
Diameter of rope(mm)	32	
layer	1	2
Capacity of rope(m)	43	90

Change Winch Main Specification

Mode I	IYJ466-138-90-32-ZPG	
Pull on the 2nd layer(kN)	138	3
Speed on the 1st layer (m/min)	26	
Work pressure diff. (MPa)	21	
Supply oil flow(L/min)	261	
Diameter of rope (mm)	32	
layer	1	2
Capacity of rope(m)	43	90

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

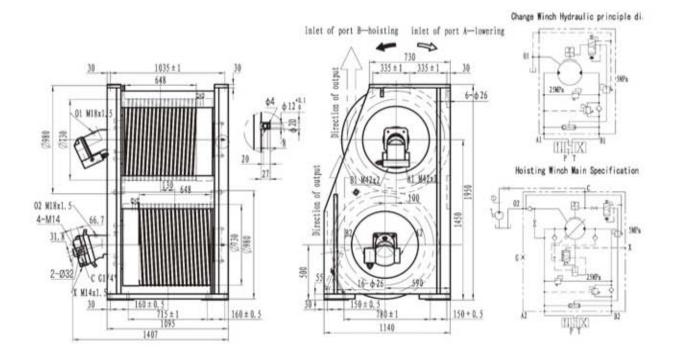
Model	1YJ466-170-90-34-ZP0	
Pull on the 2nd layer(kN)	170 45	
Speed on the 1st layer(m/min)	32	66
Work pressure diff. (MPa)	29	17
Supply oil flow(L/min)	278	
Diameter of rope(mm)	34	
layer	1	2
Capacity of rope(m)	43	90

Change Winch Main Specification

Model	IYJ466-160-90-34-ZPG	
Pull on the 2nd layer(kN)	160	
Speed on the 1st layer(m/min)	32	
Work pressure diff.(MPa)	28	
Supply oil flow(L/min)	278	
Diameter of rope(mm)	34	
layer	1	2
Capacity of rope(m)	43	90

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

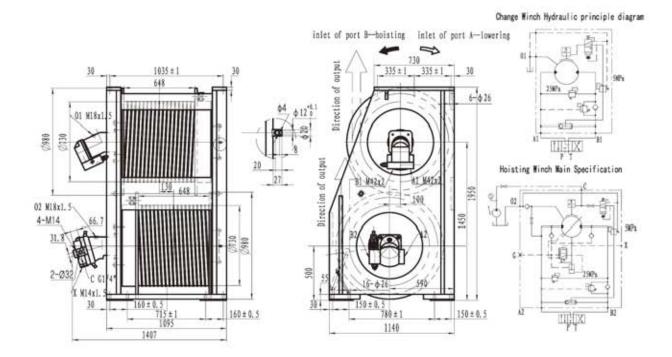
Model	1YJ466-200-85-36-ZP0	
Pull on the 2nd layer(kN)	200 53	
Speed on the 1st layer(m/min)	27	56
Work pressure diff. (MPa)	29	17
Supply oil flow(L/min)	278	
Diameter of rope(mm)	36	
layer	1	2
Capacity of rope(m)	40	85

Change Winch Main Specification

Model	1YJ466-175-90-34-ZPG	
Pull on the 2nd layer(kN)	175	
Speed on the 1st layer(m/min)	27	
Work pressure diff. (MPa)	28	
Supply oil flow(L/min)	261	
Diameter of rope(mm)	34	
layer	1	2
Capacity of rope(m)	43	90

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.





Hoisting Winch Hydraulic principle diagram

Mode I	1YJ466-140-130-34-ZP	
Pull on the 2nd layer(kN)	140 40	
Speed on the 1st layer(m/min)	38	77.7
Work pressure diff. (MPa)	29	17
Supply oil flow(L/min)	278	
Diameter of rope(mm)	34	
layer	1	2
Capacity of rope(m)	43	90

Change Winch Main Specification

Model	1YJ466-130-90-34-ZPG	
Pull on the 2nd layer(kN)	130	
Speed on the 1st layer(m/min)	38	
Work pressure diff. (MPa)	28	
Supply oil flow(L/min)	278	
Diameter of rope(mm)	34	
layer	1	2
Capacity of rope(m)	43	90

- Note: 1. The drain port of the hydraulic motor must be separately connected to the hydraulic reservoir.
 - The directional control valve should be of a "Y" or "H" type in neutral position to assure the brake and activated.
 - The winch is not designed for operation involving lifting or moving personnel.
 - 4. When there is no winch type available which meets your requirements, we ask you to contact our sales department for a specific design.